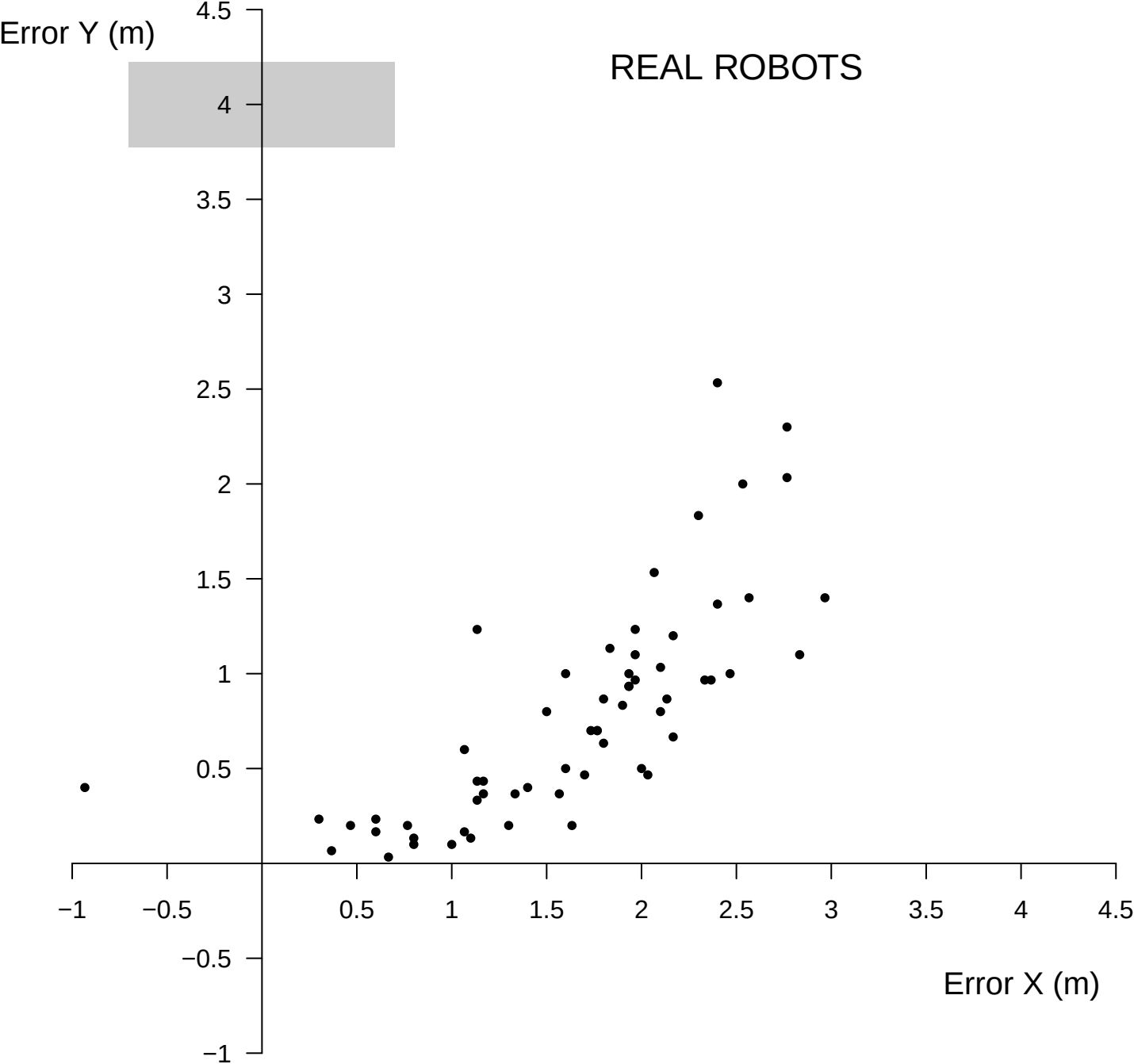
REAL ROBOTS
Error Y (m)
Error X (m)
4.5
4
3.5
3
2.5
2
1.5
1
0.5
−0.5
−1
−1
−0.5
0.5
1
1.5
2
2.5
3
3.5
4
4.5